

AN3154 Application note

CAN protocol used in the STM32 bootloader

Introduction

This application note describes the CAN protocol used in the STM32 microcontroller bootloader. It details each supported command. For more information about the CAN hardware resources and requirements for your device bootloader, please refer to the application note AN2606 "STM32 system memory boot mode".

Table 1. Applicable products

| Туре | Part number or product series |
|------------------|---|
| Microcontrollers | STM32F1 series: - STM32F105xx, STM32F107xx, STM32F2 series STM32F4 series: - STM32F405xx, STM32F407xx - STM32F415xx, STM32F417xx - STM32F427xx, STM32F429xx - STM32F437xx, STM32F439xx |

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1 Bootloader code sequence

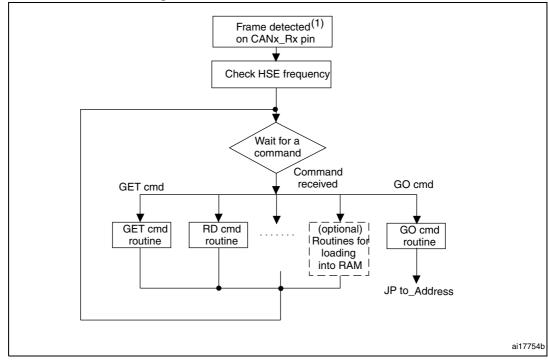


Figure 1. Bootloader for STM32 with CAN

1. it is recommended to send a frame with a Standard ID = 0x79.

Once the system memory boot mode is entered and the STM32 device has been configured (for more details refer to application note AN2606 "STM32 system memory boot mode"), the bootloader code waits for a frame on the CANx_Rx pin. When a detection occurs the CAN bootloader firmware starts to check the external clock frequency.

Figure 2 shows the flowchart of the frequency check.

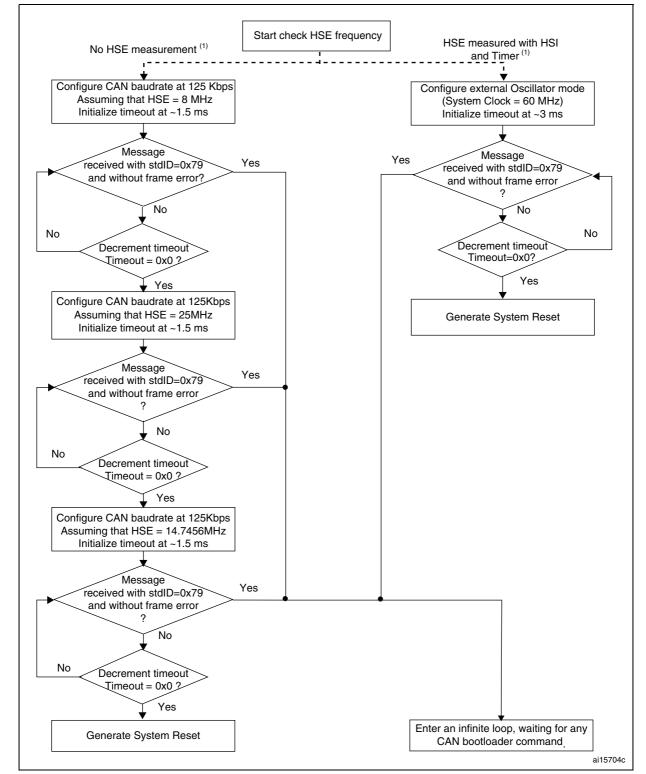


Figure 2. Check HSE frequency

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For some devices, the HSE frequency is calculated using HSI oscillator connected to a timer. For other
devices, this measurement is not implemented. For the devices without HSE frequency measurement, only
the flow represented on the left is executed, while for the devices with HSE frequency measurement, only
the flow on the right is executed. To know which flow is relative to your device, please refer to AN2606.

AN3154 CAN settings

Next, the code initializes the serial interface accordingly. Using this calculated baud rate, an acknowledge byte (0x79) is returned to the host, which signals that the STM32 is ready to receive commands.

2 CAN settings

The STM32 CAN is compliant with the 2.0A and B (active) specifications with a bitrate up to 1 Mbit/s. It can receive and transmit standard frames with 11-bit identifiers as well as extended frames with 29-bit identifiers.

Figure 3 shows a CAN frame that uses the standard identifier only.

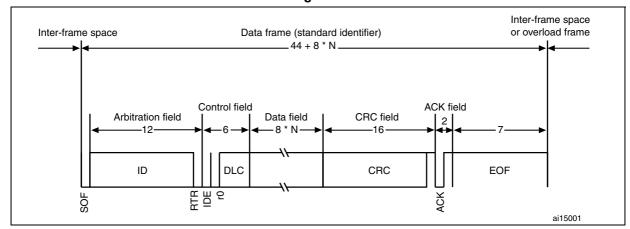


Figure 3. CAN frame

In this application, the CAN settings are:

- Standard identifier (not extended)
- Bitrate: at the beginning it is 125 kbps; during runtime it can be changed via the speed command to achieve a maximum bit rate of 1 Mbps.

The transmit settings (from the STM32 to the host) are:

- Tx mailbox0: On
- Tx mailbox1 and Tx mailbox2: Off
- Tx identifier: (0x00, 0x01, 0x02, v03, 0x11, 0x21, 0x31, 0x43, 0x63, 0x73, 0x82, 0x92)

The receive settings (from the host to the STM32) are:

- Synchronization byte, 0x79, is in the RX identifier and not in the data field.
- RX identifier depends on the command (0x00, 0x01, 0x02, 0x03, 0x11, 0x21, 0x31, 0x43, 0x63, 0x73, 0x82, 0x92).
- Error checking: If the error field (bit [6:4] in the CAN_ESR register) is different from 000b, the message is discarded and a NACK is sent to the host.
- In FIFO overrun condition, the message is discarded and a NACK is sent to the host.
- Incoming messages can contain from 1 to 8 data bytes.

Note: The CAN bootloader firmware supports only one node at a time. This means that CAN Network Management is not supported by the firmware.



The supported commands are listed in *Table 2*. Each command is further described in this section.

Command **Command code Command description** Gets the version and the allowed commands Get⁽¹⁾ 0x00 supported by the current version of the bootloader Get Version & Gets the bootloader version and the Read Protection 0x01 Read Protection Status⁽¹⁾ status of the Flash memory Get ID⁽¹⁾ 0x02 Gets the chip ID The speed command allows the baud rate for CAN Speed 0x03 run-time to be changed. Reads up to 256 bytes of memory starting from an Read Memory⁽²⁾ 0x11 address specified by the application Jumps to user application code located in the internal Go⁽²⁾ 0x21 Flash memory or in SRAM Writes up to 256 bytes to the RAM or Flash memory Write Memory⁽²⁾ 0x31 starting from an address specified by the application Erase⁽²⁾ 0x43 Erases from one to all the Flash memory sectors 0x63 Write Protect Enables the write protection for some sectors Disables the write protection for all Flash memory Write Unprotect 0x73 sectors

Table 2. CAN bootloader commands

Enables the read protection

Disables the read protection

Communication safety

Readout Protect(1)

Readout Unprotect(1)

Each packet is either accepted (ACK answer) or discarded (NACK answer):

0x82

0x92

- ACK message = 0x79
- NACK message = 0x1F

3.1 Get command

The Get command allows the host to get the version of the bootloader and the supported commands. When the bootloader receives the get command, it transmits the bootloader version and the supported command codes to the host.

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Read protection – When the RDP (read protection) option is active, only this limited subset of commands is available. All other commands are NACKed and have no effect on the device. Once the RDP has been removed, the other commands become active.

Please refer to STM32 product datasheet and AN2606 "STM32 microcontroller system memory boot mode" to know which memory spaces are valid for these commands.

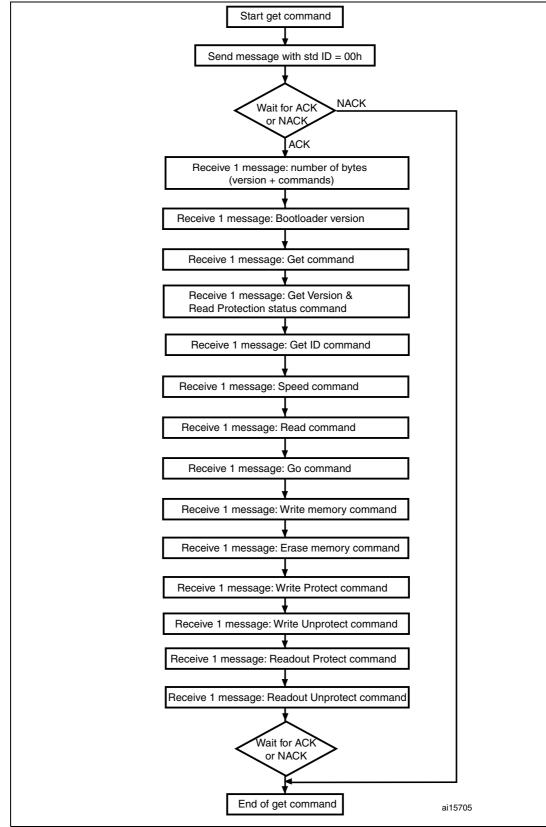


Figure 4. Get command: host side

The host sends messages as follows:

Command message: Std ID = 0x00, data length code (DLC) = 'not important'.

Start get command

Received message
with ID = 0x00?

Yes

Send ACK message

Send NACK message

Send 1 message: Number of bytes
(version + commands)

Send 12 messages: Supported commands

Send ACK message

End of get command

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Figure 5. Get command: device side

The STM32 sends messages as follows:

Message 1: Std ID = 0x00, DLC = 1, data = 0x79 - ACK

Message 2: Std ID = 0x00, DLC = 1 data = N = 12 = the number of bytes to be sent -1 $(1 \le N + 1 \le 256)$

Message 3: Std ID = 0x00, DLC = 1, data = bootloader version (0 < version ≤ 255)

Message 4: Std ID = 0x00, DLC = 1, data = 0x00 - Get command

Message 5: Std ID = 0x00, DLC = 1, data = 0x01 - Get Version & Read Protection

Status command

Message 6: Std ID = 0x00, DLC = 1, data = 0x02 - Get ID command

Message 7: Std ID = 0x00, DLC = 1, data = 0x03 - Speed command

Message 8: Std ID = 0x00, DLC = 1, data = 0x11 - Read memory command

Message 9: Std ID = 0x00, DLC = 1, data = 0x21 - Go command

Message 10: Std ID = 0x00, DLC = 1, data = 0x31 - Write memory command

Message 11: Std ID = 0x00, DLC = 1, data = 0x43 - Erase memory command

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Message 12: Std ID = 0x00, DLC = 1, data = 0x63 - Write Protect command

Message 13: Std ID = 0x00, DLC = 1, data = 0x73 - Write Unprotect command

Message 14: Std ID = 0x00, DLC = 1, data = 82h - Readout Protect command

Message 15: Std ID = 0x00, DLC = 1, data = 92h - Readout Unprotect command

Message 1: Std ID = 0x00, DLC = 1, data = 0x79- ACK

3.2 Get Version & Read Protection Status command

The Get Version & Read Protection Status command is used to get the bootloader version and the read protection status. When the bootloader receives the command, it transmits the information described below (version and 2 dummy bytes having value 0x00) to the host.

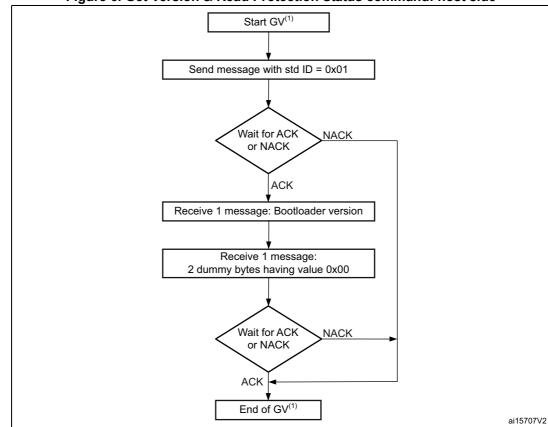


Figure 6. Get Version & Read Protection Status command: host side

1. GV = Get Version & Read Protection Status.

The host sends messages as follows:

Command message: Std ID = 0x01, data length code (DLC) = 'not important'.

ACK Message contain: Std ID = 0x01, DLC = 1, data = 0x79 - ACK

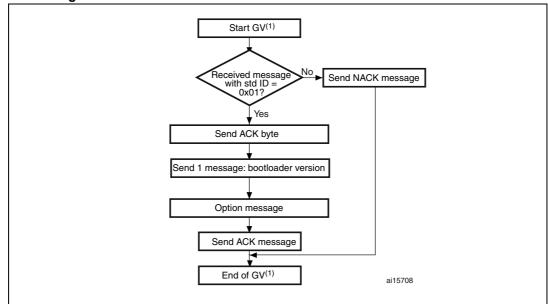


Figure 7. Get Version & Read Protection Status command: device side

1. GV = Get Version & Read Protection Status.

The STM32 sends messages as follows:

Message 1: Std ID = 0x01, DLC = 1, data = ACK

Message 2: Std ID = 0x01, DLC = 1, data[0] = bootloader version (0 < version \leq 255), example: 0x10 = Version 1.0

Message 3: Option message 1: Std ID = 0x01, DLC = 2, data = 0x00(byte1 and byte2)

Message 4: Std ID = 0x01, DLC = 1, data = ACK

3.3 Get ID command

The Get ID command is used to get the version of the chip ID (identification). When the bootloader receives the command, it transmits the product ID to the host.

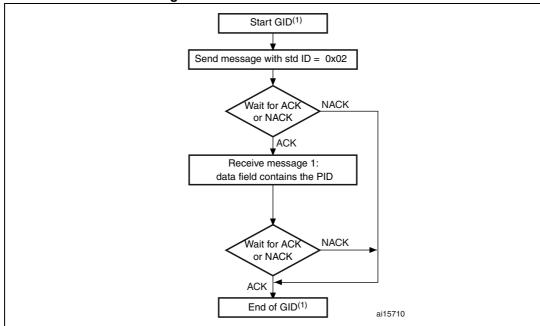


Figure 8. Get ID command: host side

- 1. GID = Get ID.
- PID stands for product ID. Byte 1 is the MSB and byte 2, the LSB of the address. Refer to Section 3.1: Get command for more details about the PID of the device you are using.

The host sends messages as follows:

Command message: Std ID = 0x02, data length code (DLC) = 'not important'.

ACK Message contain: Std ID = 0x02, DLC = 1, data = 0x79 - ACK

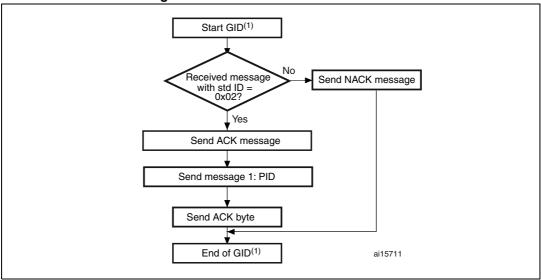


Figure 9. Get ID command: device side

- 1. GID = Get ID.
- 2. PID stands for product ID. Byte 1 is the MSB and byte 2 is LSB of the address.

The STM32 sends the bytes as follows:

Message 1: Std ID = 0x02, DLC = 1, data = ACK with DLC except for current message and ACKs.

Message 2: Std ID = 0x02, DLC = N (the number of bytes - 1. For STM32, N = 1), data = PID with byte 0 is MSB and byte N is the LSB of the product ID

Message 3: Std ID = 0x02, DLC = 1, data = ACK = 0x79

3.4 Speed command

The speed command allows the baud rate for CAN run-time to be changed. It can be used only if CAN is the peripheral being used.

A system reset is generated if the CAN receives the correct message but the operation to set the new baudrate fails, which prevents it from entering or leaving initialization mode.

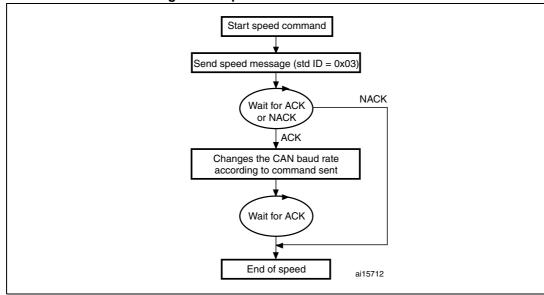


Figure 10. Speed command: host side

 After setting the new baud rate, the bootloader sends the ACK message. Therefore, the host sets its baud rate while waiting for the ACK.

The host sends the message as follows:

Command message: Std ID = 0x03, DLC = 0x01, data[0] = XXh where XXh takes the following values depending on the baud rate to be set:

- 0x01 -> baud rate = 125 kbps
- 0x02 -> baud rate = 250 kbps
- 0x03 -> baud rate = 500 kbps
- 0x04 -> baud rate = 1 Mbps

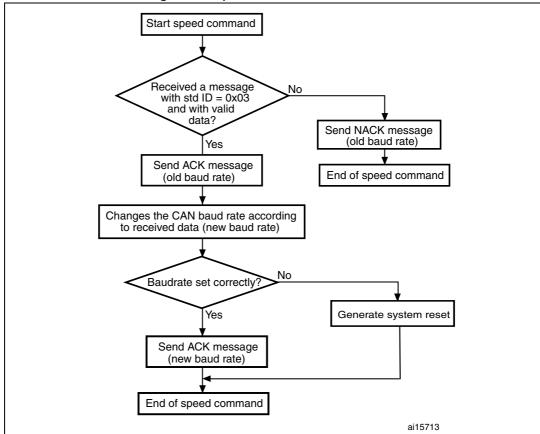


Figure 11. Speed command: device side

The STM32 sends the bytes as follows:

Message 1: Std ID = 0x03, DLC = 1, data[0] = ACK= 0x79: with old baudrate if the receive

message is correct else data[0] = NACK= 0x1F

Message 2: Std ID = 0x03, DLC = 1, data[0] = ACK = 0x79 with new baudrate

3.5 Read Memory command

The Read Memory command is used to read data from any valid memory address (see note) in RAM, Flash memory and in the information block (System memory or option byte areas).

When the bootloader receives the Read Memory command, it starts to verify the contents of the message:

- ID of the command is correct or not
- ReadOutProtection is disabled or enabled
- Address to be read is valid or not

If the message content is correct it transmits an ACK message otherwise it transmits a NACK message.

After sending an ACK message, then it transmits the required data to the application ((N + 1) bytes) via (N+1) messages /8 (since each message contains 8 bytes), starting from the received address.

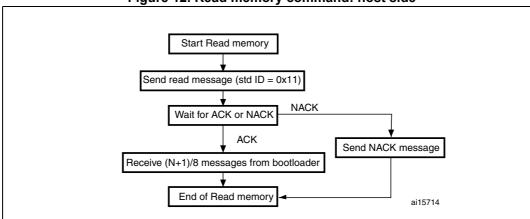


Figure 12. Read memory command: host side

The host sends messages as follows:

Command message:

Std ID = 0x11, DLC = 0x05, data[0] = 0xXX: MSB of the address... data[3] = 0xYY: LSB of the address, data[4] = N: number of bytes to be read (where $0 < N \le 255$).

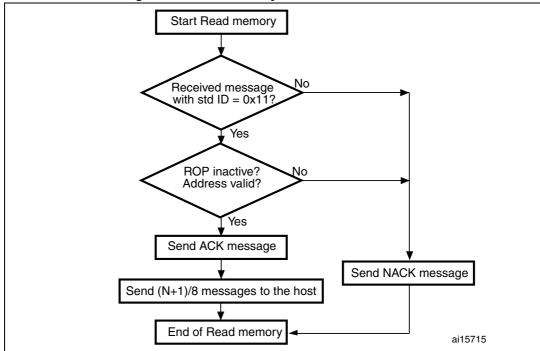


Figure 13. Read memory command: device side

The STM32 sends messages as follows:

ACK message: Std ID = 0x11, DLC = 1, data[0] = ACK if content of the command is correct else data[0] = NACK

Data message (N+1) / 8: Std ID = 0x11, DLC = Number of Byte, data[0] = 0xXX... data[Number of Byte - 1] = 0xYY

ACK message: Std ID = 0x11, DLC = 1, data[0] = ACK

3.6 Go command

The Go command is used to execute the downloaded code or any other code by branching to an address specified by the application. When the bootloader receives the Go command, it starts if the message contains the following valid information:

- ID of the command is correct or not
- ReadOutProtection is disabled or enabled
- Branch destination address is valid or not(data[0] is the address MSB and data[3] 4 is LSB

If the message content is correct it transmits an ACK message otherwise it transmits a NACK message.

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After sending an ACK message to the application, the bootloader firmware performs the following:

- it initializes the registers of the peripherals used by the bootloader to their default reset values
- it initializes the user application's main stack pointer
- it jumps to the memory location programmed in the received 'address + 4' (which corresponds to the address of the application's reset handler).
 For example if the received address is 0x0800 0000, the bootloader will jump to the memory location programmed at address 0x0800 0004.
 In general, the host should send the base address where the application to jump to is programmed

Note: 1 The Jump to the application works only if the user application sets the vector table correctly to point to the application address.

- 2 The valid addresses for the Go command are in RAM or Flash memory (refer to Section 3.1: Get command for more details about the valid memory addresses for the device you are using). All other addresses are considered not valid and are NACKed by the device.
- 3 When an application is loaded into RAM and then a jump is made to it, the program must be configured to run with an offset to avoid overlapping with the first RAM memory used by the bootloader firmware (refer to Section 3.1: Get command for more details about the RAM offset for the device you are using).

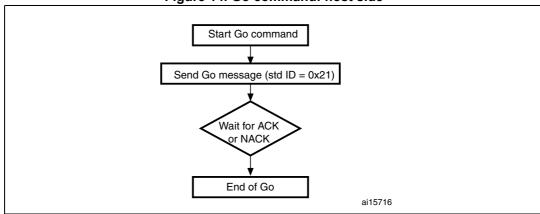


Figure 14. Go command: host side

1. See product datasheet for valid addresses.

The host sends the bytes as follows

Go command message: Std ID = 0x21, DLC = 0x04, data[0] = 0xXX: MSB address,...data[3] = 0xYY LSB address.

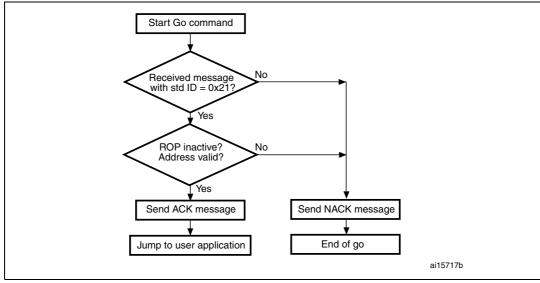


Figure 15. Go command: device side

The STM32 send the messages as follows:

ACK message: Std ID = 0x21, DLC = 1, data[0] = ACK if content of the command is correct else data[0] = NACK

3.7 Write Memory command

The Write Memory command is used to write data to any valid memory address (see note) of RAM, Flash memory, or Option byte area. When the bootloader receives the Write Memory command, (message with 5 bytes data length, data[0] is the address MSB, data[3] is the LSB and data[4] is the number of data bytes to be received), it then checks the received address. For the Option byte area, the start address must be the base address of the Option byte area (see note) to avoid writing inopportunely in this area.

Note: Refer to Section 3.1: Get command for more details about the valid memory addresses for the device you are using.

If the received address is valid, the bootloader transmits an ACK message, otherwise it transmits a NACK message and aborts the command. When the address is valid, the bootloader:

- Receives the user data (N bytes) so the device receives N/8 messages (each message contains 8 data bytes)
- Programs the user data into memory starting from the received address
- At the end of the command, if the write operation was successful, the bootloader transmits the ACK message; otherwise it transmits a NACK message to the application and aborts the command

The maximum length of the block to be written for the STM32 is 256 bytes.

If the Write Memory command is issued to the Option byte area, all options are erased before writing the new values, and at the end of the command the bootloader generates a system Reset to take into account the new configuration of the option byte.

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Note: 1 When writing to the RAM, you should take care not to overlap the first RAM memory used by the bootloader firmware.

2 No error is returned when performing write operations on write protected sectors.

Start Write memory

Send Write message (std ID = 0x31)

Wait for ACK or NACK
Or NACK

Send the data messages. At same time, the host checks whether it received a NACK message

Wait for ACK or NACK

Send the data messages. At same time, the host checks whether it received a NACK message

Wait for ACK or NACK

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Figure 16. Write Memory command: host side

Note:

If the start address is invalid, the command is NACKed by the device.

The host sends the messages as follows:

Command message: Std ID = 0x31, DLC = 0x05, data[0] = 0xXX: MSB address,..., data[3] = 0xYY: LSB address, data[4] = N-1 (number of bytes to be written - 1), $0 < N \le 255$).

then the host send N/8 message

Data message: Std ID = 0x31, DLC_1 = to 8, data = byte_11, ... byte_18...

Data message_M: Std ID = 0x04, DLC_M = 1 to 8, data = byte_m1, ..., byte_M8

Note: 1 $DLC_1 + DLC_2 + ... DLC_M = 256 \text{ maximum}$

- 2 After each message the host receives the ACK or NACK message from the device
- 3 The bootloader does not check the standard ID of the data, so any ID from 0h to 0xFF can be used. It is recommended to use 0x04.

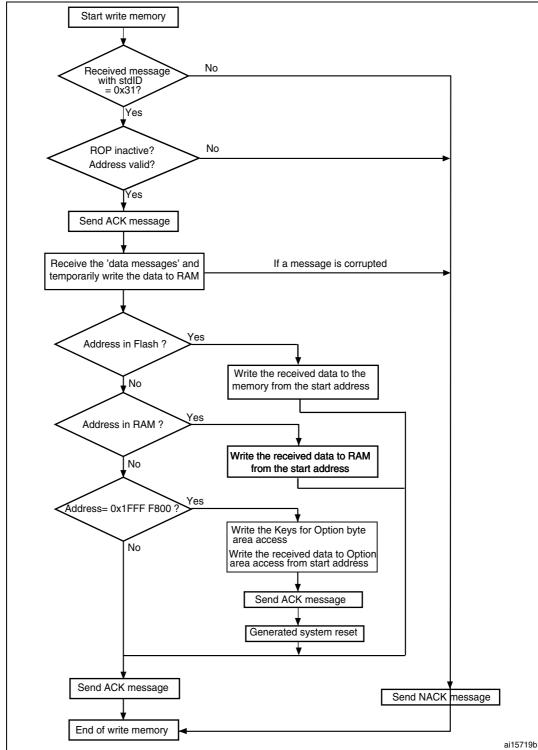


Figure 17. Write memory command: device side

The STM32 sends messages as follows:

ACK message: Std ID = 0x31, DLC = 1, data[0] = ACK if the content of the command is correct else data[0] = NACK



After each received message, the device will send an ACK if the content of the command is correct else a NACK. However, as described in *Figure 17*, after receiving all the 'data messages' (N/8 messages) and temporarily write the data to RAM, if none of the messages content is corrupted, the bootloader will write the N bytes at the requested address (Flash memory, RAM or option byte), then if the write operation is successfully completed, device will send an ACK message to the host.

In other terms, after sending the N/8 messages, host will receive two successive ACK; the first will be sent by the device if the last message of the N/8 is correctly received, and the second ACK will be sent after writing correctly the N/8 message at the requested address

3.8 Erase Memory command

The Erase Memory command allows the host to erase Flash memory pages. When the bootloader receives the Erase Memory command and ROP is disabled, it transmits the ACK message to the host. After the transmission of the ACK message, the bootloader checks if data[0] is equal to 0xFF, if it is the case a global memory erase operation will be started and when finished it sends ACK message. Otherwise (data[0] is different from 0xFF), the bootloader will start the memory page(s) erase as defined by the host, and after each page erase it sends ACK or NACK message.

Erase Memory command specifications:

- 1. The bootloader receives one message that contains N, the number of pages to be erased 1.
 - N = 255 is reserved for global erase requests. For 0 \leq N \leq 254, N + 1 pages are erased.
- 2. The bootloader receives (N + 1) bytes, each byte containing a page number

Note: No error is returned when performing erase operations on write protected sectors.



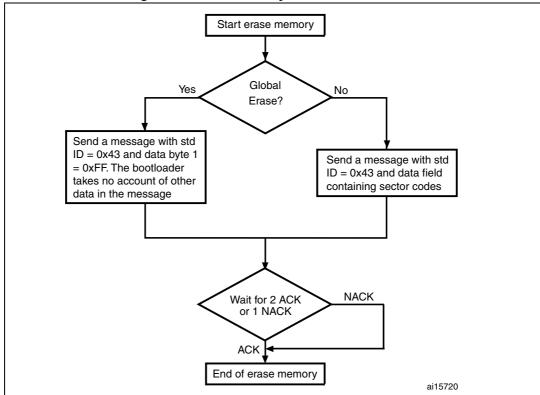


Figure 18. Erase Memory command: host side

The host sends the message as follows:

The ID contains the command type (0x43):

- Total erase message: Std ID = 0x43, DLC = 0x01, data = 0xFF.
- Erase sector by sector message: Std ID = 0x43, DLC = 0x01 to 0x08, data = see product datasheet.

In case of page by page erase, after each message the host receives the ACK or NACK message from the device.

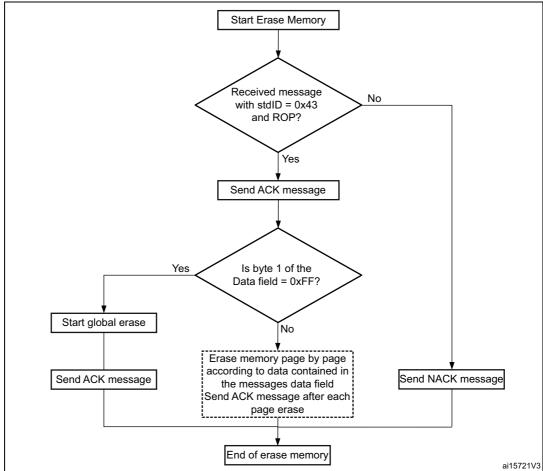


Figure 19. Erase Memory command: device side

The STM32 sends messages as follows:

ACK message: Std ID = 0x43, DLC = 1, data[0] = ACK if content of the command is correct and ROP is not active else data[0] = NACK

3.9 Write Protect command

The Write Protect command is used to enable the write protection for some or all Flash memory sectors. When the bootloader receives the Write Protect command, it transmits the ACK message to the host if ROP is disabled else it transmits NACK.

After the transmission of the ACK byte, the bootloader waits to receive the Flash memory sector codes from the application.

At the end of the Write Protect command, the bootloader transmits the ACK message and generates a system Reset to take into account the new configuration of the option byte.

Note: 1 Refer to Section 3.1: Get command for more details about the sector size for the device you are using.

2 The total number of sectors and the sector number to be protected are not checked, this means that no error is returned when a command is passed with a wrong number of sectors to be protected or a wrong sector number.

If a second Write Protect command is executed, the Flash memory sectors that were protected by the first command become unprotected and only the sectors passed within the second Write Protect command become protected.

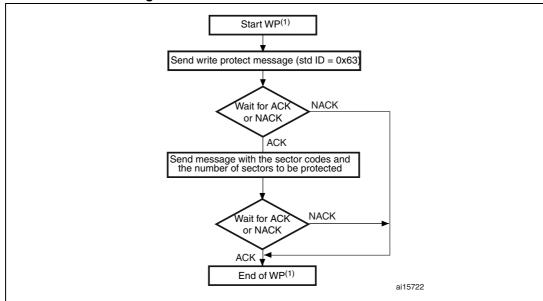


Figure 20. Write Protect command: host side

1. WP = Write Protect.

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The host sends messages as follows:

Command message: Std ID = 0x63, DLC = 0x01, data[0] = N (where $0 < N \le 255$).

Command message: Std ID = 0x63, DLC = 0x01..08, data[0] = N (where $0 < N \le 255$).

After each message the host receives the ACK or NACK message from the device.

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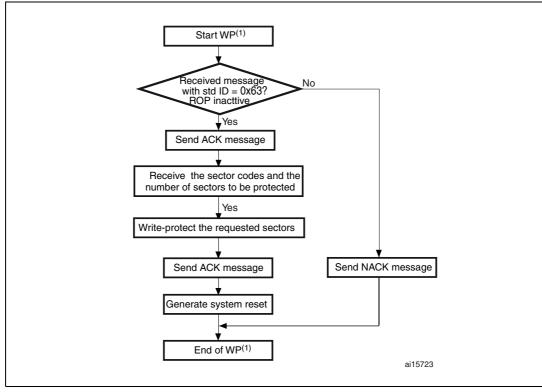


Figure 21. Write Protect command: device side

1. WP = Write Protect

The STM32 sends messages as follows:

ACK message: Std ID = 0x63, DLC = 1, data[0] = ACK if the content of the command is correct and ROP is not active else data[0] = NACK.

3.10 Write Unprotect command

The Write Unprotect command is used to disable the write protection of all the Flash memory sectors. When the bootloader receives the Write Unprotect command, it transmits the ACK message to the host if ROP is disabled else it transmits NACK. After the transmission of the ACK message, the bootloader disables the write protection of all the Flash memory sectors.

At the end of the Write Unprotect command, the bootloader transmits the ACK message and generates a system Reset to take into account the new configuration of the option byte.

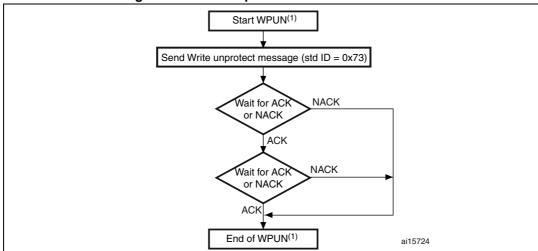
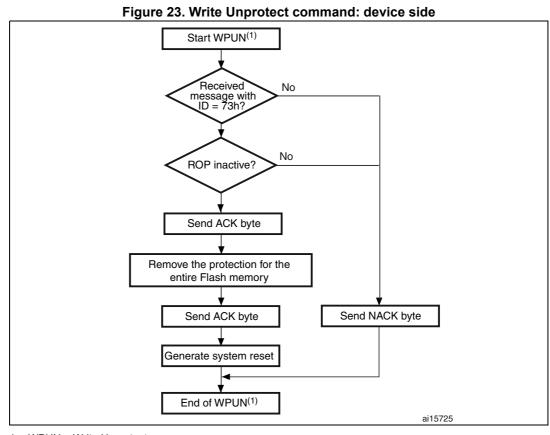


Figure 22. Write Unprotect command: host side

1. WPUN = Write Unprotect.

The host sends messages as follows:

Command message: Std ID = 0x73, DLC = 0x01, data = 00.



1. WPUN = Write Unprotect.

The STM32 sends messages as follows:

ACK message: Std ID = 0x73, DLC = 1, data[0] = ACK if the content of the command is correct and ROP is not active else data[0] = NACK.

3.11 Readout Protect command

The Readout Protect command is used to enable the Flash memory read protection. When the bootloader receives the Readout Protect command, it transmits the ACK message to the host if ROP is disabled else it transmits NACK. After the transmission of the ACK message, the bootloader enables the read protection for the Flash memory.

At the end of the Readout Protect command, the bootloader transmits the ACK message and generates a system Reset to take into account the new configuration of the option byte.

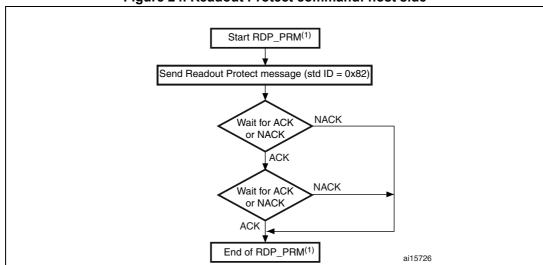


Figure 24. Readout Protect command: host side

1. RDP_PRM = Readout Protect.

The host sends the messages as follows

Command message: Std ID = 0x82, DLC = 0x01, data[0] = 00.

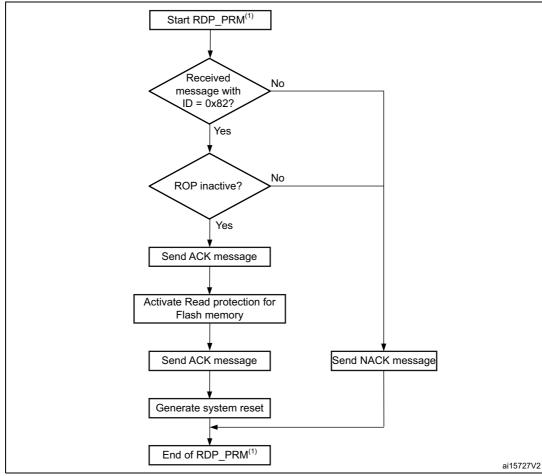


Figure 25. Readout Protect command: device side

1. RDP_PRM = Readout Protect

The STM32 sends messages as follows:

ACK message: Std ID = 0x82, DLC = 1, data[0] = ACK if the content of the command is correct and ROP is not active else data[0] = NACK.

3.12 Readout Unprotect command

The Readout Unprotect command is used to disable the Flash memory read protection. When the bootloader receives the Readout Unprotect command, it transmits the ACK message to the host. After the transmission of the ACK message, the bootloader erases all the Flash memory sectors and it disables the read protection for the entire Flash memory. If the erase operation is successful, the bootloader deactivates the RDP.

At the end of the Readout Unprotect command, the bootloader transmits an ACK message and generates a system Reset to take into account the new configuration of the option bytes.

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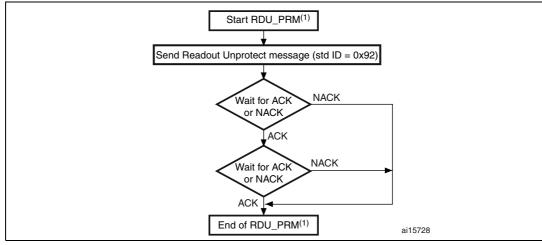


Figure 26. Readout Unprotect command: host side

1. RDU_PRM = Readout Unprotect.

The host sends messages as follows

Command message: Std ID = 0x92, DLC = 0x01, data = 00.

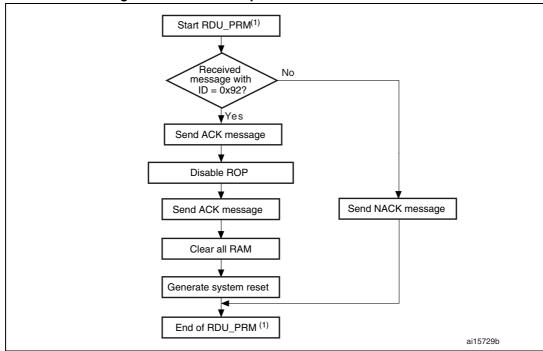


Figure 27. Readout Unprotect command: device side

1. RDU_PRM = Readout Unprotect.

The STM32 sends messages as follows:

ACK message: Std ID = 0x92, DLC = 1, data[0] = ACK if the content of the command is correct and ROP is not active else data[0] = NACK.



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4 Bootloader protocol version evolution

Table 3 lists the bootloader versions.

Table 3. Bootloader protocol versions

| Version | Description |
|---------|-----------------------------|
| V2.0 | Initial bootloader version. |

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AN3154 Revision history

5 Revision history

Table 4. Document revision history

| Date | Revision | Changes |
|-------------|----------|---|
| 09-Mar-2010 | 1 | Initial release. |
| 15-Apr-2011 | 2 | Updated Figure 2: Check HSE frequency and added Note 1. |
| 22-Apr-2011 | 3 | Update Std ID for message 2 in Section 3.4: Speed command. |
| 24-Oct-2012 | 4 | Updated Chapter 3.2: Get Version & Read Protection Status command Figure 6: Get Version & Read Protection Status command: host side Chapter 3.7: Write Memory command Chapter 3.8: Erase Memory command Figure 19: Erase Memory command: device side Chapter 3.9: Write Protect command Figure 25: Readout Protect command: device side |
| 02-May-2014 | 5 | Updated Table 1: Applicable products and Table 2: CAN bootloader commands. Removed Section dedicated to Device-dependent bootloader parameters. Updated Section 3.5: Read Memory command and Section 3.7: Write Memory command. |

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